

27	Mode de freinage	Réglage du mode de freinage Bit 0 Freins ABC, voltage plus élevé côté droit 1 Freins ABC, voltage plus élevé côté gauche 2 ZIMO HLU 3 Freinage sur DC, si la polarité est inverse au sens de marche 4 Freinage sur DC, si la polarité est identique au sens de marche	Value 1 2 4 8 16		24
28	RailCom® configuration	Réglages RailCom® Bit 0 Canal rendu libre pour la diffusion d'adresse 1 Connection de données autorisée sur canal 2 7 RailCom® Plus, déclaration automatique de la locomotive activée	Value 1 2 128		131
29	Registre de configuration	Le CV le plus complexe des normes DCC. Ce registre contient des informations importantes, utilisées seulement en mode DCC Bit 0 Sens normal de marche Sens de marche inversé 1 14 pas de vitesse (seulement en mode DCC) 28 ou 128 pas de vitesse (seulement en mode DCC) 2 Mode analogique désactivé Mode analogique autorisé 3 RailCom® désactivé RailCom® autorisé 4 Courbe de vitesse par CV 2,5,6 Courbe de vitesse par CV 67-96V 5 Adresses courtes (CV1) en mode DCC Adresses longues (CV 17+18) en mode DCC	Value 0 1 0 2 0 4 0 8 0 16 0 32		30
31	Index register H	Page de sélection pour CV 257-512	16	16	
32	Index register L	Page de sélection pour CV 257-512	0, 2, 3	0	
49	Configuration étendue	Réglage des fonctions de freinage et de contrôle de la FCEM Bit 0 Compensation de charge désactivée Compensation de charge activée 1 Moteur DC- Fréquence de modulation du moteur 15 KHz Moteur DC- Fréquence de modulation du moteur 30 KHz 2 Mode Märklin® Delta désactivé Mode Märklin® Delta activé 3 Mode seconde adresse Märklin® désactivé Mode seconde adresse Märklin® activé 4 Détection automatique de pas de vitesse activée Détection des pas de vitesse DCC désactivé 5 Désactivation du mode bouton de fonction LGB® Activation du mode bouton de fonction LGB® 6 Désactivation du mode Manuel Zimo® Activation du mode Manuel Zimo®	Value 0 1 0 2 0 4 0 8 0 16 0 32 0 64	0 - 255	17
50	Mode analogique	Selection of allowed analogue modes Bit 0 Désactivation du mode analogique AC Activation du mode analogique AC 1 Désactivation du mode analogique DC Activation du mode analogique DC	Value 0 1 0 2	0 - 3	2
52	Paramètre K de contrôle de compensation de charge en marche lente	Composant «K» du micro contrôleur interne pour les pas de marche lente. Définit l'effet de la compensation de charge. Plus la valeur est élevée plus l'effet de contrôle de la FCEM est important.	0 - 255	20	
53	Contrôle du voltage de référence	Définit le voltage de la FCEM que le moteur peut générer à la vitesse maximum. Plus le moteur est performant, plus cette valeur peut-être élevée.	0 - 255	110	
54	Paramètre K de contrôle de compensation de charge	Composant «K» du micro contrôleur interne. Définit l'effet de la compensation de charge. Plus la valeur est élevée plus l'effet de contrôle de la FCEM est important.	0 - 255	30	
55	Paramètre I de contrôle de compensation de charge	Composant «I» du micro contrôleur interne. Définit l'inertie du moteur. Plus l'inertie du moteur est importante (large volant d'inertie..) plus cette valeur doit être basse.	1 - 255	40	
56	Champ d'application du contrôle de compensation de charge	0-100%. Définit en pourcentage jusqu'à quelle vitesse le contrôle de compensation de charge sera actif . une valeur de 32 indique que la compensation de charge sera active jusqu'à mi-vitesse.	1 - 192	220	
63	Volume du son	Volume général de effets sonores	0 - 192	192	
124	Configuration étendue #2	Réglages additionnels importants pour décodeurs LokSound Bit 0 Désactive le sens de marche Bit bi-directionnel: active le sens de marche lors du changement de direction 1 Désactive le verrouillage du décodeur avec les CV 15/16 Active le verrouillage du décodeur avec les CV 15/16 2 Désactive le protocole série pour moteurs C-Sinus Active le protocole série pour moteurs C-Sinus 4 Régulation de fréquence variable Régulation de fréquence constante	Value 0 1 0 2 0 4 0 16		20
125	Voltage de démarrage DC analogique		0 - 255	90	
126	Vitesse maximum DC analogique		0 - 255	130	
127	Voltage de démarrage AC		0 - 255	90	
128	Vitesse maximum AC		0 - 255	150	



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CE UK 12V --- 14+
Service Sheet HJD-B-061hp
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FEATURES:

- Factory preset address for the locomotive is 03.
- 50 khz frequency for a smoother motor control.
- The V.5 decoder supports DCC.
- 14, 28 or 128 selectable speed steps for DCC systems.
- Load compensation function.
- Outputs overload protection for all functions.
- Audio amplifier 3W 32 Ohms.

DECODER PARAMETERS ADJUSTING:

The V.5 LokSound decoder (128 Mbit) controls several parameters. You can find a list of the most important ones at the end of this instructions. Each parameter (CV) can be configured independently using its respective command.

DCC Systems (Lenz, Intellibox, etc.)

It is much easier to modify the parameters if you have a DCC compatible digital system or an Intellibox. Please, read the corresponding chapter in your system manual (DCC decoders programming). The LokSound decoder V.5 supports any NMRA programming system.

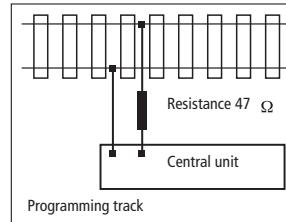
ANALOG OPERATION

When using conventional transformer, the locomotive movement will be similar to that of a locomotive without a decoder. The locomotive will only start its running when receiving a minimum voltage between 5.5 and 6 volts, as the decoder will not work with a lower tension. Please note the following warnings: The decoder installed in your Jouef locomotive has been specifically adapted for this model and it should only be used in this particular model. Always disconnect the decoder from the power supply before doing any work on it.

If removing the speaker is necessary for maintenance purposes, please handle it very carefully.

Do not put any pressure on it or touch the speaker membrane.

The reset function is very convenient, as you can set the original factory values again at any time. You can use this function with DCC and Motorola systems. To use this function, type "8" in CV 8 or "08" in register "08".



When programming using Lenz, Uhlenbrock or Arnold equipment, please refer to their programming instructions. If the error message "err02" is displayed during programming with Lenz or Arnold equipment, a 47 Ohmresistor (0.5 Watt or higher) must be inserted between one of the two supply cables and the programming track.

KEY	FUNCTION	SOUNDSLOTS	VOLUME CVs	VALUE
F0	Front light			
F1	Sound on/off	2,20	267, 411	128, 128
F2	Air horn high pitched	3	275	128
F3	Air horn low pitched	4	283	128
F4	Rear red light on/off			
F5	Compressor	6	299	60
F6	Shunting mode/shunting speed acceleration/brake time off/on			
F7	Curve squeal	15	371	75
F8	Rail clank 1	1	259	160
F9	Compressed air let off	9	323	60
F10	Conductor's signal	10	331	80
F11	Coupler clank	8	315	100
F12	Sanding valve	11	339	30
F13	Release brake	13	355	50
F14	Random sounds off/on (Shift mode)			
F15	Short airhorn 1	21	419	128
F16	Open/close cab door	12	347	128
F17	Rail clank 2	17	387	85
F18	Sound fader			
F19	Short airhorn 2	22	427	128
F20	Warning signal 1 (air horn tunnel)	19	403	128
F21	Warning signal 2 (air horn station platform)	16	379	128
F22	Tachograph	23	435	35
F23	Brake squeal sound off/on			
F24				
F25				
F26				
F27				

CV	NAME	DESCRIPTION	RANGER	VALUE
1	Loco address.	Locomotive address	1-127	3
2	Start voltage.	Sets the minimum speed of the engine	1-75	3
3	Acceleration.	This value multiplied by 0.869 is the time from stop to maximum speed.	0-255	11
4	Deceleration.	This value multiplied by 0.869 is the time from maximum speed to stop.	0-255	11
5	Maximum speed.	Maximum speed of engine	0-64	255
6	Medium speed.	Average engine speed	0-64	88
8	Manufacturer's ID.	Manufacturer's ID (ESU). Set CV8 to value 8 for automatic resetting.		151
13	Analogue mode F1-F8.	Status of functions F1 to F8 in analogue mode.	0-255	129
		Bit Function Value		
		0 F1 1		
		1 F2 2		
		2 F3 4		
		3 F4 8		
		4 F5 16		
		5 F6 32		
		6 F7 64		
		7 F8 128		
17	Extended address	Extended engine addressing address of engine		192
18				128



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12V --- 14+
Service Sheet HJD-B-061hp

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27	Brake modus	Allowed brake modus		24
		Bit Function Value		
	0	ABC brakes, voltage higher on right side	1	
	1	ABC brakes, voltage higher on left side	2	
	2	ZIMO HLU brakes active	4	
	3	Brake on DC, if polarity is vice-versa to the driving direction	8	
	4	Brake on DC, if polarity is the same as driving direction	16	
28	RailCom® configuration	Settings for RailCom®		131
		Bit Function Value		
	0	Channel 1 given free for address broadcast	1	
	1	Data connection on channel 2 allowed	2	
	7	RailCom® Plus automatical loco registration active	128	
29	Configuration register	The most complex CV within the DCC standards. This register contains important information, which is only relevant in DCC mode.		30
		Bit Function Value		
	0	Normal direction of travel. Forward becomes reverse.	0 1	
	1	14 speed steps (only in DCC mode). 28 or 128 speed steps (only in DCC mode).	0 2	
	2	Analogue mode off. Analogue mode permitted.	0 4	
	3	RailCom® switched off RailCom® allowed	0 8	
	4	Speed curve through CV 2, 5, 6. Speed curve through CV 67 - 96V.	0 16	
	5	Short addresses (CV 1) in DCC-mode. Long addresses (CV 17+18) in DCC-mode	0 32	
31	Index register H	Selection page for CV257-512	16	16
32	Index register L	Selection page for CV257-512	0, 2, 3	0
49	Extended configuration	Activate support for brake sections or switch off Back EMF control	0 - 255	17
		Bit Function Value		
	0	Load control off Load control activated	0 1	
	1	DC motor PWM frequency - 15 kHz pulse frequency DC motor PWM frequency - 30 kHz pulse frequency	0 2	
	2	Märklin® delta mode - Delta mode off Märklin® delta mode - Delta mode on	0 4	
	3	Märklin® second address off Märklin® second address on	0 8	
	4	Automatic speed step detection DCC speed step detection off	0 16	
	5	Disable LGB® function button mode Enable LGB® function button mode	0 32	
	6	Disable Zimo® Manual Function Enable Zimo® Manual Function	0 64	
50	Analogue mode	Selection of allowed analogue modes	0 - 3	2
		Bit Function Value		
	0	Disable AC Analog Mode Enable AC Analog Mode	0 1	
	1	Disable DC Analog Mode Enable DC Analog Mode	0 2	
52	Load control parameter «K» for slow driving	“K”-component of the internal PI-controller for the low speed steps. Defines the effect of load control. The higher the value, the stronger the effect of Back EMF control.	0 - 255	20
53	Control Reference voltage	Defines the Back EMF voltage, which the motor should generate at maximum speed. The higher the efficiency of the motor, the higher this value may be set. If the engine does not reach maximum speed, reduce this parameter.	0 - 255	110
54	Load control parameter K	“K”-component of the internal PI-controller. Defines the effect of load control. The higher the value, the stronger the effect of Back EMF control.	0 - 255	30
55	Load control parameter I	“I”-component of the internal PI-controller. Defines the momentum (inertia) of the motor. The higher the momentum of the motor (large flywheel or bigger motor diameter, the lower this value has to be set).	1 - 255	40
56	Operating range of load control	0 - 100% Defines up to which speed in % load control will be active. A value of 32 indicates that load control will be effective up to half speed.	1 - 192	220
63	Sound volume	Volume of running and additional sounds.	0 - 192	192
124	Extended Configuration #2	Additional important settings for LokSound Decoders Zusätzliche wichtige Einstellungen der LokSound-Decoder		20
		Bit Function Value		
	0	Disable driving firention Bi-directional bit: Enable driving direction when shifting direction	0 1	
	1	Disable decoder lock with CV 15/16 Enable decoder lock with CV 15/16	0 2	
	2	Disable serial protocol for C-Sinus Enable serial protocol for C-Sinus	0 4	
	4	Adaptive regulation freqency Constant regulation freqency	0 16	
125	Starting voltage Analog DC		0 - 255	90
126	Maximum speed Analog DC		0 - 255	130
127	Starting voltage AC		0 - 255	90
128	Maximum speed Analog AC		0 - 255	150